

1. Neural networks at IDC

Introduction:

- According to *Sereno and Patnaik, (1993)*, the neural network based initial wave type classification system was created in early 1990s (as an extension of a two class system P vs. S) and became part of IMS v3 (IMS is here *Intelligent Monitoring System*)
- Station-specific weights were trained using analyst-reviewed data for two three-component (3-C) stations which had enough data
- For the rest of stations **average** weights yielded by training using data from multiple stations were produced
- Around 2002 the networks have been re-trained using data from STKA station which has a low noise, see (*J. Wang, 2002*)
- Since then, these weights are used as weights for all 3C stations in IMS (IMS stands here for *International Monitoring System*)
- m_b SNR screening was introduced later to improve classification performance of the noise
- Our goal is to investigate if the classification performance of 3-C seismic stations can be improved by:
 - Re-training of legacy multilayer perceptrons taking extracted features on input using more station-specific data
 - Replacement of the legacy classifier by a new one based on convolution neural networks taking waveform on input

2. Re-training of current neural networks

Problem statement:

- Initial wave type is determined using StaPro (Station Processing) software for all IMS arrivals detected at IDC
 - $iwt \in \{\text{noise, regional S (Sn, Lg, Rg, Sx), regional P (Pn, Pg, Px), teleseismic (P, tx)}\}$
 - initial wave type is further refined to more specific wave types
- For 3-component (3-C) stations the system relies on a cascade of three binary classifiers implemented as neural networks (NNs)
- Current NN weights were derived in 2002 using data from a single station (STKA) and are applied to **all** 3-C stations worldwide
- We now have much more station specific data reviewed by analysts
- Our goal is to investigate if the classification performance of 3-C seismic stations can be improved by re-training using more **station-specific** data

Three stage classifier:

- The system comprises of a cascade of three binary classifiers
 - Step 1:** the system tries to distinguish between noise **N** and a signal **{regS, regP, tele}**
 - Step 2:** if signal: is it **regS** or **{regP, tele}**?
 - Step 3:** if **{regP, tele}**: is it **regP** or **tele**?
- All three classifiers are implemented as a multilayer perceptron (neural network)
- After NN classification, there is a revision stage of possible **T→regP** change and **regS** refinement using a Bayesian model

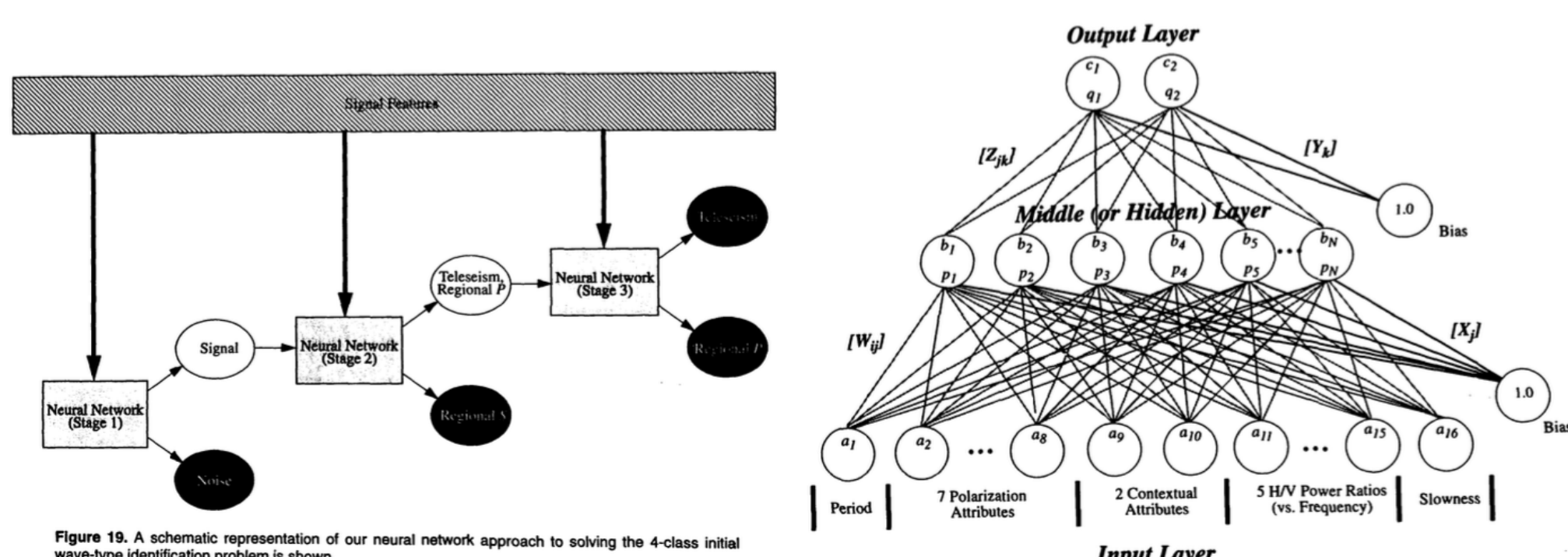


Figure 1: Representation of the three stage classifier and topology of each of its stage. Illustrations from the original paper (*Sereno and Patnaik, 1993*)

Retraining of current neural networks contd.

Classification features:

#	Feature	Description	Source	Norm.
1	period	Dominant period of the detected phase	ARRIVAL	
2	rect	Signal rectilinearity	APMA	
3	plans	Signal planarity	APMA	
4	inang ₁	Long-axis incidence angle	APMA	/90
5	inang ₃	Short-axis incidence angle	APMA	/90
6	hm _{xmn}	Ratio of the maximum to minimum horizontal amplitude	APMA	log ₁₀
7	hvr _{rat}	Ratio of horizontal-to-vertical power	APMA	log ₁₀
8	hvr _{rat}	Similar to hvr _{rat} , measured at the time of max 3C amplitude	APMA	log ₁₀
9	N _{after} - N _{before}	Diff. between the no. of arrivals before and after within ±60s	on the fly	/10
10	T _{after} - T _{before}	Mean time diff. between arrivals before and after within ±60s	on the fly	/100
11	htov ₁	Horiz. to vert. power ratio in oct. freq. band centered at 0.25 Hz	AMP3C	log ₁₀
12	htov ₂	Horiz. to vert. power ratio in oct. freq. band centered at 0.5 Hz	AMP3C	log ₁₀
13	htov ₃	Horiz. to vert. power ratio in oct. freq. band centered at 1.0 Hz	AMP3C	log ₁₀
14	htov ₄	Horiz. to vert. power ratio in oct. freq. band centered at 2.0 Hz	AMP3C	log ₁₀
15	htov ₅	Horiz. to vert. power ratio in oct. freq. band centered at 4.0 Hz	AMP3C	log ₁₀

2.1 m_b SNR screening

- m_b SNR screening is prepended to NN classifier in StaPro
- All 3-C arrivals are checked by this screening and labeled as noise if $m_b < m_b^{min}$, m_b^{min} is a station specific threshold
- Its purpose is to identify noise phases using m_b and exclude them from classification where significant amount of them is classified as a real phase due to poor classification performance
- Drawback:** this simple criterion labels also significant number of associated phases as noise (increases *N-phase rate*) and they do not enter NN classification

m_b SNR screening – evaluation of effects:

- Results are produced using current URZ OPS weights without m_b SNR (left) and with m_b SNR (right)
- 17999 arrivals detected Jan – May 2017 (1581 associated in LEB, 16418 noise phases)

	old weights without m_b SNR				old weights with m_b SNR			
	N	S	P	T	N	S	P	T
N	4289	99	9	108	8312	113	35	167
S	2371	134	0	138	1743	124	0	128
P	3305	30	266	277	2097	26	237	244
T	6452	9	34	477	4265	9	37	461
				28.7% (assoc. 55.5%)	50.7% (assoc. 51.9%)			
				N-phase rate 13.6%	N-phase rate 19.9%			

2.2 Dataset description

- Training:** analyst reviewed URZ automatic arrivals **2003 – 2016**
 - Signal phases are all automatic arrivals associated to LEB (arrivals) with re-timing ≤ 2 seconds (29252 arrivals)
 - Noise phases are selected randomly from all automatic arrivals classified as noise and not associated to LEB
 - Training data is split on training and validation data in ratio 9:1
 - Dataset is highly imbalanced – we employed weighted loss during training
- Testing:** analyst reviewed URZ automatic arrivals **Jan – May 2017**

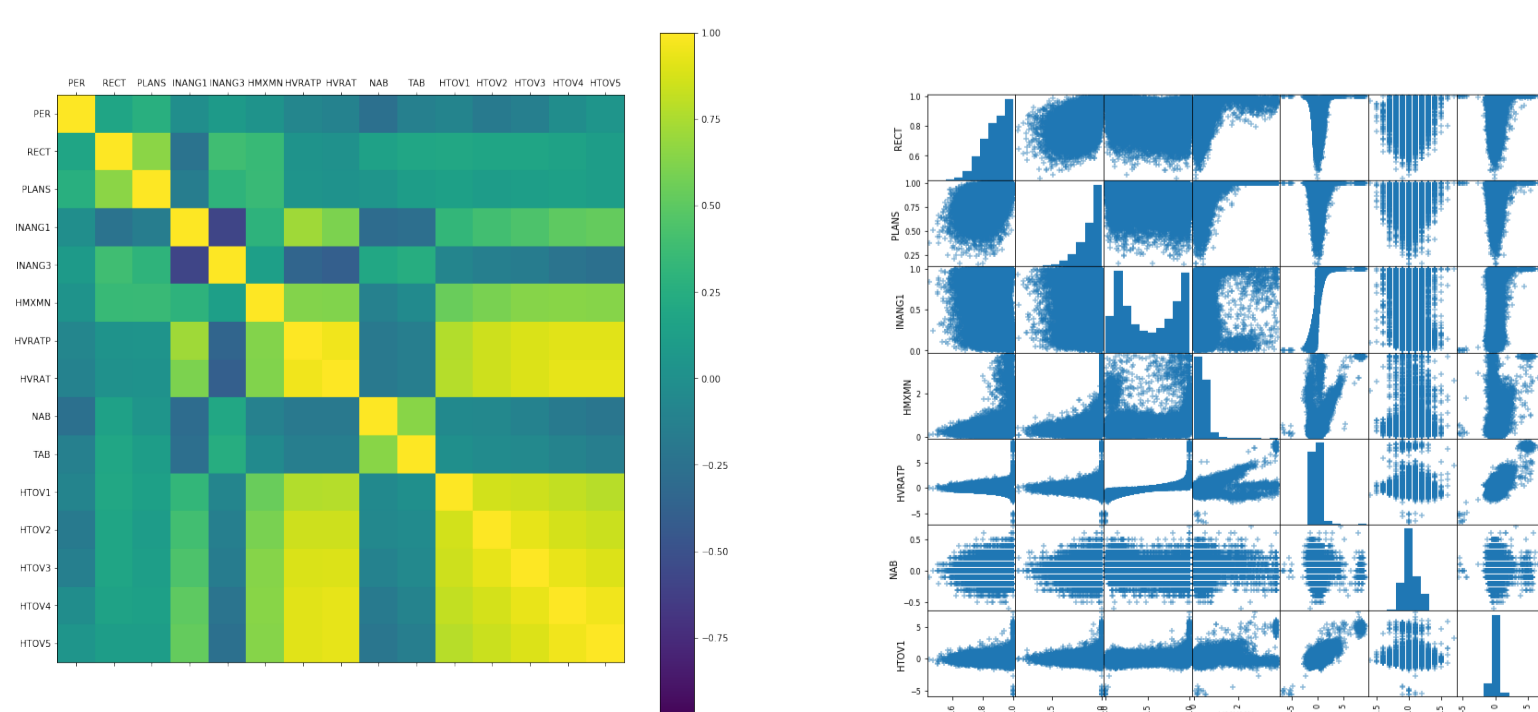


Figure 2: Features properties: correlation matrix (left), scatter plot matrix (right).

2.3 Re-training results

Test set results:

- Offline comparison of confusion matrices for old and new weights Jan - May 2017
- Test set results indicate that we can improve both classification accuracy and N-phase rate at the same time by re-training (without the need of m_b SNR screening)

	old, m_b SNR, T→regP ref.				new weights				new, T→regP ref.			
	N	S	P	T	N	S	P	T	N	S	P	T
N	8312	113	35	167	9740	48	12	43	9740	48	12	43
S	1743	124	0	128	2477	220	2	221	2477	220	2	221
P	2097	26	237	244	991	2	195	68	1948	3	254	191
T	4265	9	37	461	3209	2	100	669	2252	1	41	546
				50.7% (assoc. 51.9%)	60.1% (assoc. 68.5%)				59.8% (assoc. 64.5%)			
				N-phase rate: 19.9%	N-phase rate: 6.5%				N-phase rate: 6.5%			

Development LAN results:

- 2018/07/25: weights in DVL, m_b SNR screening turned off for URZ (m_b^{min} set to 0)
- Evaluation performed on arrivals between 2018/08/01 and 2018/09/30 (2 months, 4243 arrivals, 494 associated to LEB)
- DVL and OPS arrivals matched by proximity in time and azimuth

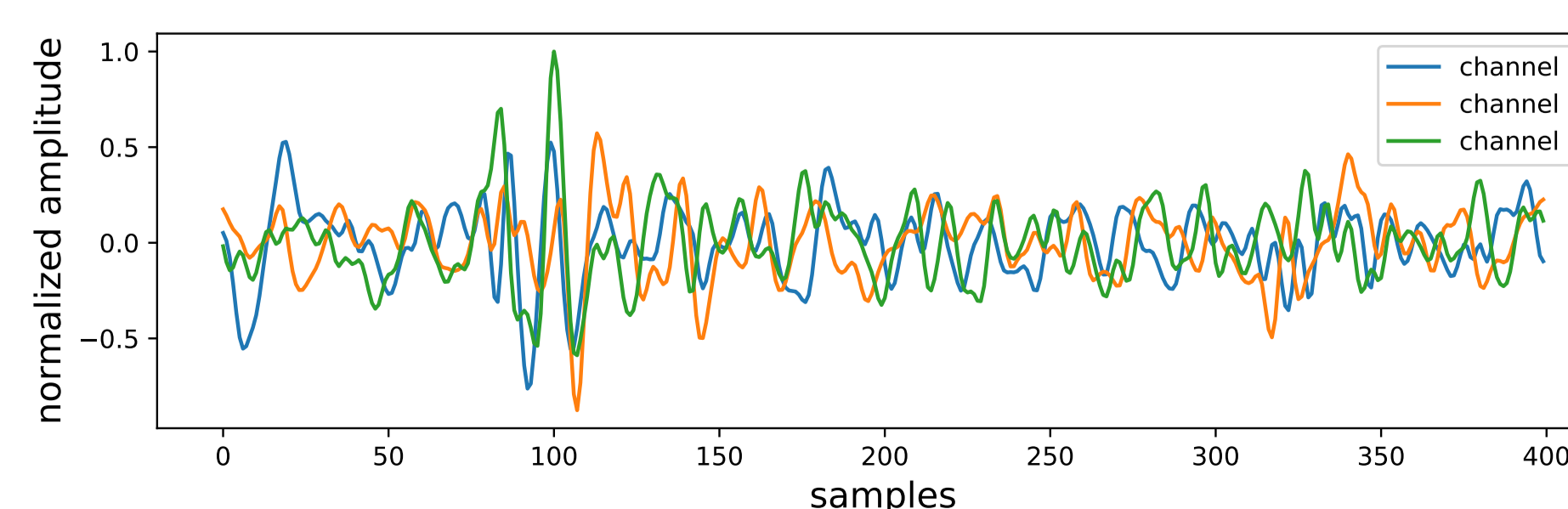
	OPS: old, m_b SNR, T→regP ref.				DVL: new, T→regP ref.			
	N	S	P	T	N	S	P	T
N	1879	33	9	48	2042	8	3	11
S	439	56	2	39	719	83	2	64
P	497	2	76	83	503	1	84	60
T	934	1	10	135	485	0	8	170
				50.6% (assoc. 54.0%)	56.1% (assoc. 68.2%)			
				N-phase rate: 17.0%	N-phase rate: 4.5%			

3. Convolution network

- Recently, works on successful application of convolutional neural network (CNNs) for phase identification have been published, .e.g. *Ross et al. (2018)* and *Woollam et al. (2019)*
- CNNs take waveform on input so the extraction of (subjective and possibly highly correlated) features can be avoided
- We take arrivals from the STA/LTA detector and try to train a single CNN for phase classification, i.e. with probabilities for all four classes on output
- As class labels for training we use labels given to associated phases by analysts, all other arrivals are considered as noise
 - This could bias the dataset — some real seismic phases are not associated because of their redundancy during event creation

Dataset:

- URZ 2003-2016 data — 10s waveforms (400 samples) around STA/LTA arrivals from all three channels
- Dataset heavily unbalanced: (268103, 1113, 6364, 78289) representatives for (N,S,P,T)
- Channels pass-band filtered normalized by max. abs. amplitude of the sample
- 10% of representatives of each class used for testing



3.1 Convolutional model and results

Convolutional model:

- We use Keras to implement and train the network on GPU:
 - Activation function rectified linear (ReLU) and softmax for the output layer
 - Loss categorical cross-entropy, optimizer Adam
 - Training stopped by after 48 epochs with with batch size 512
 - Class weights (0.05, 100, 10, 1) for classes (N,S,P,T)

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Layer (Type) Output Shape Param #
-----
conv1d_1 (Conv1D) (None, 391, 100) 3100
activation_4 (Activation) (None, 391, 100) 0
conv1d_2 (Conv1D) (None, 382, 100) 100100
activation_5 (Activation) (None, 382, 100) 0
max_pooling1d_1 (MaxPooling1D) (None, 127, 100) 0
dropout_1 (Dropout) (None, 127, 100) 0
conv1d_3 (Conv1D) (None, 118, 100) 100100
activation_6 (Activation) (None, 118, 100) 0
global_average_pooling1d_1 (GlobalAveragePooling1D) (None, 100) 0
flatten_1 (Flatten) (None, 100) 0
dense_2 (Dense) (None, 32) 3232
activation_7 (Activation) (None, 32) 0
dense_3 (Dense) (None, 4) 132
Total params: 206,664
Trainable params: 206,664
Non-trainable params: 0
    
```

Figure 3: Keras model summary of our convolution network.

First results seem to be promising:

	Convolutional network			
	N	S	P	T
N	16342	7	2	152
S	2244	82	2	116
P	2032	4	590	876
T	6192	18	42	6685
				accuracy 67.0% (assoc. 85%)
				N-phase rate 1.8%

Discussion

Re-training of current classifier:

- Both accuracy and noise improved after retraining using station-specific data
- At the same time, number of associated phases classified as noise in automatic processing decreased mainly due to removal of m_b SNR screening criterion
- Retraining of other 3C stations will follow
- Experiments with CNNs:**
 - Experiments with CNNs give promising results with potential to supersede the old 3-stage multilayer perceptron classifier
 - Performance could be probably further improved by reviewing training dataset on seismic phases labeled as noise

References

- Ross, Z. E., et al. *Generalized seismic phase detection with deep learning*. Bulletin of the Seismological Society of America 108.5A (2018): 2894-2901.
- Sereno, T. and Patnaik, G., *Initial Wave-type Identification with Neural Networks and its Contribution to Automated Processing in IMS Version 3.0*, Tech. Rep., SAIC-93/1219, 1993
- Wang, J., *Adaptive training of neural networks for automatic seismic phase identification*. Monitoring the Comprehensive Nuclear-Test-Ban Treaty: Data Processing and Infrasound (2002): 1021-1041.
- Woollam, J., et al. *Conv. neural network for seismic phase classification, performance demonstration over a local seismic network*. Seis. Research Letters 90.2A (2019): 491-502.

Disclaimer

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