

# *Machine learning for emulation of seismic-phase travel times in 3D earth models*

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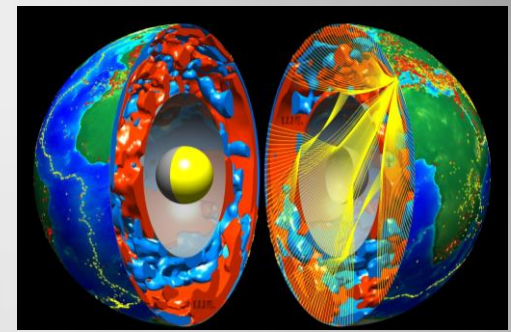
 **Lawrence Livermore  
National Laboratory**



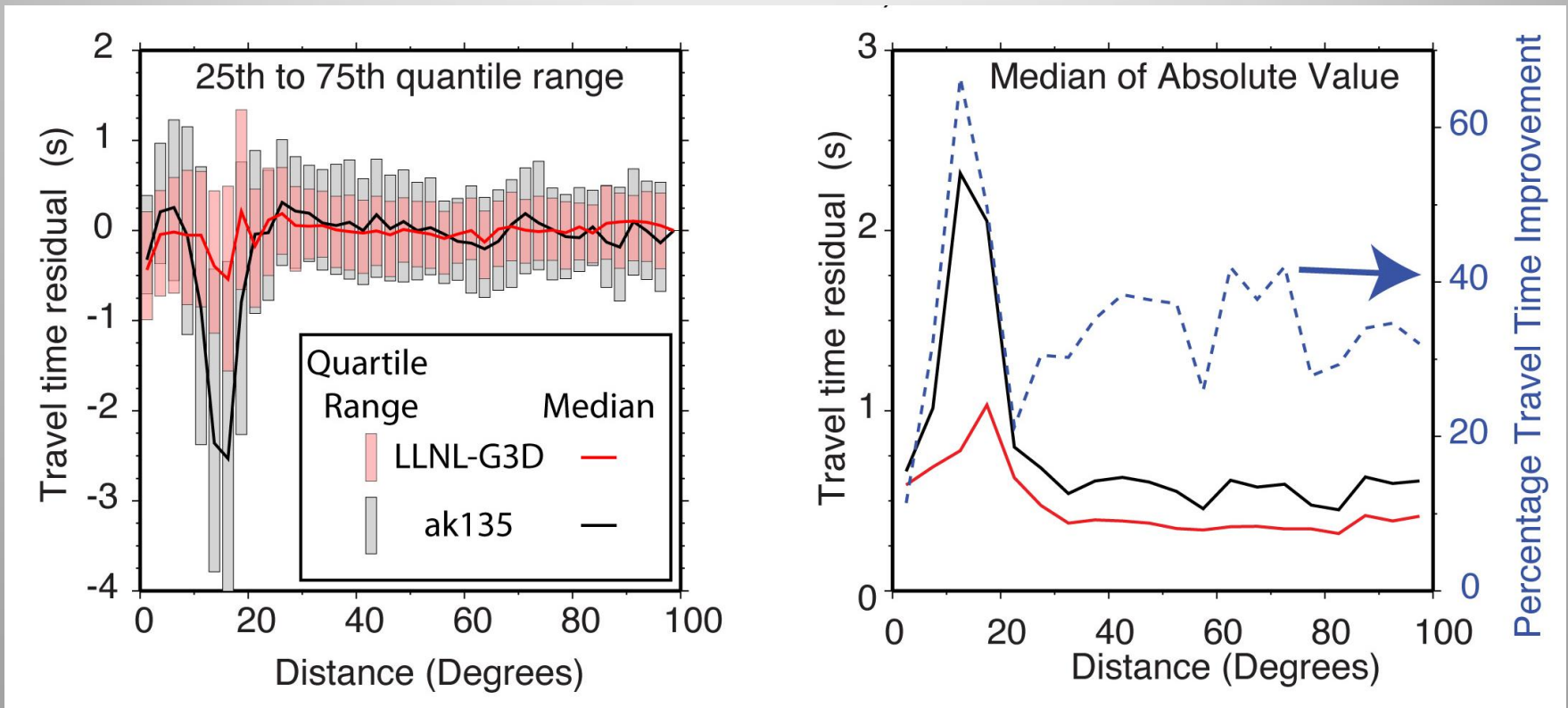
LLNL-PRES-777338

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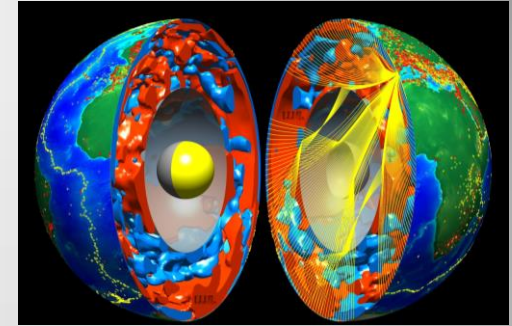
# Global 3D models significantly reduce prediction error of seismological observables



## Improved travel time prediction

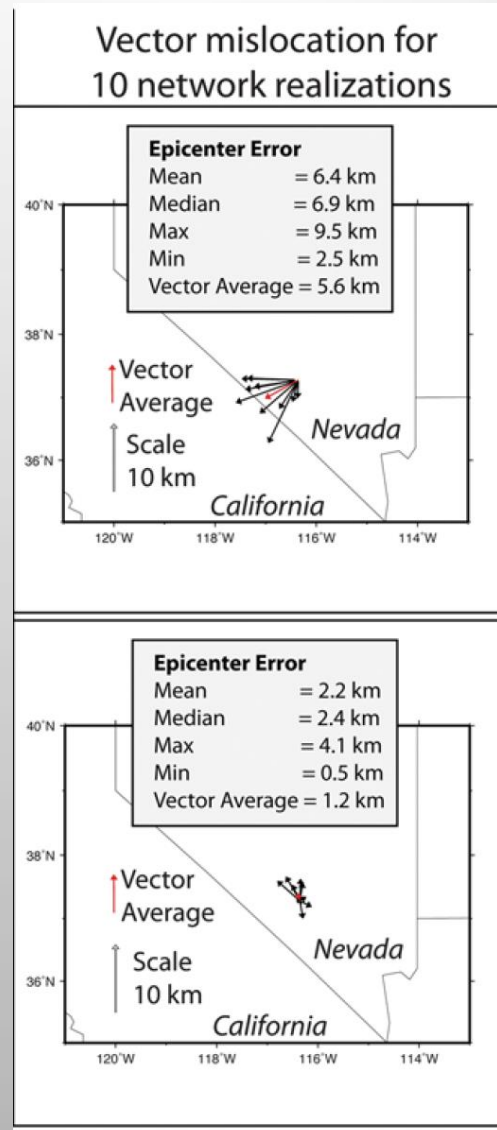
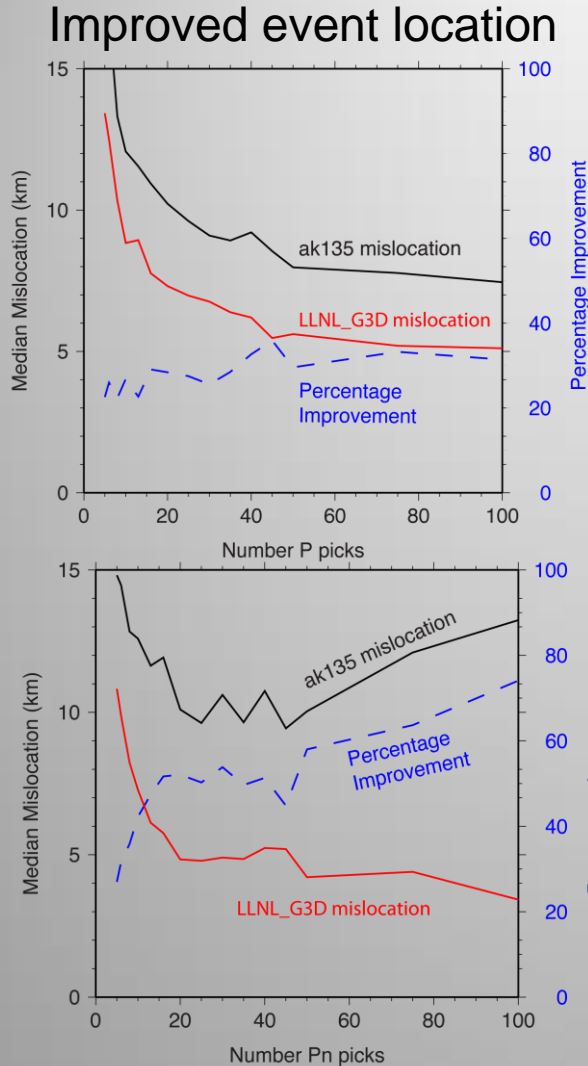


# Improved travel time prediction errors reduce event location bias and overall mislocation



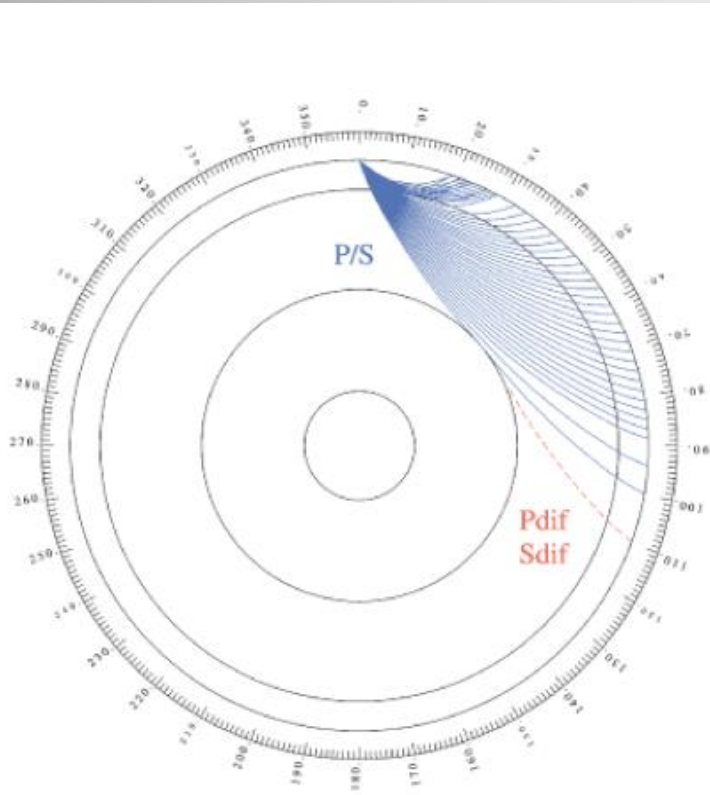
Left  
Summary epicenter errors for global set of ground truth events

Right  
Epicenter bias when using a 1-D model (top) and a global 3D model (bottom)

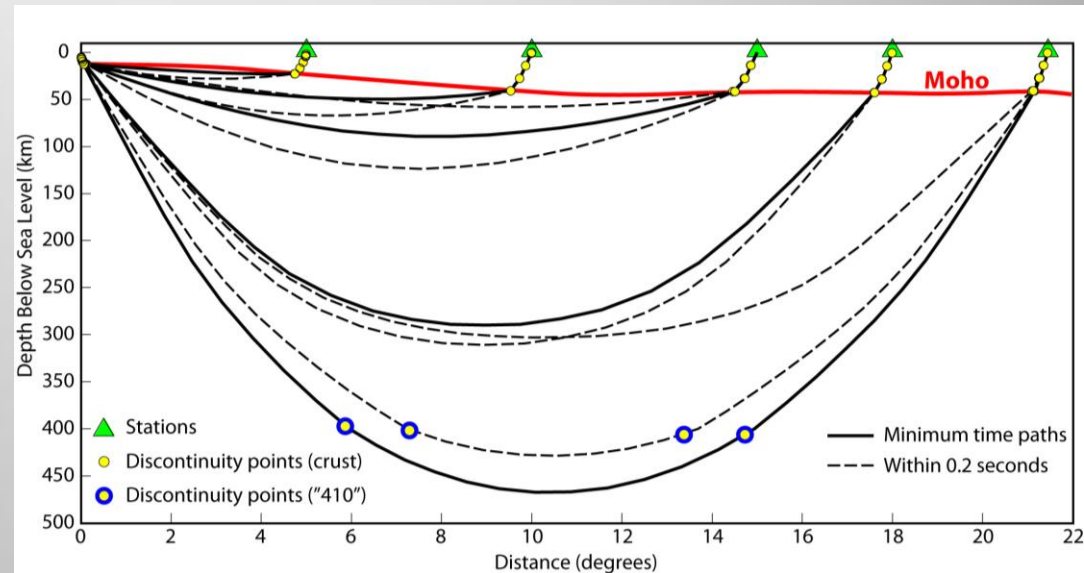


# Computation time through 3D models is too slow for operational monitoring

Computation time for simple teleseismic rays can be less than 0.1 second



Computation time for multi-pathed regional rays can be over 1.0 seconds



Location of a single event using a 3D model may require several minutes of travel time calculations

# The current approach for utilization of 3D models is approximation or precomputation

## **Approximation:**

The Regional Seismic Travel Time (RSTT) method can be used for regional phases (Myers et al., 2010)

- ✓ Millisecond calculation time
- ✓ Accurate when mantle structure can be approximated with a gradient
  - Limited to regional distances ( $< \sim 15^\circ$ )

## **Precomputation**

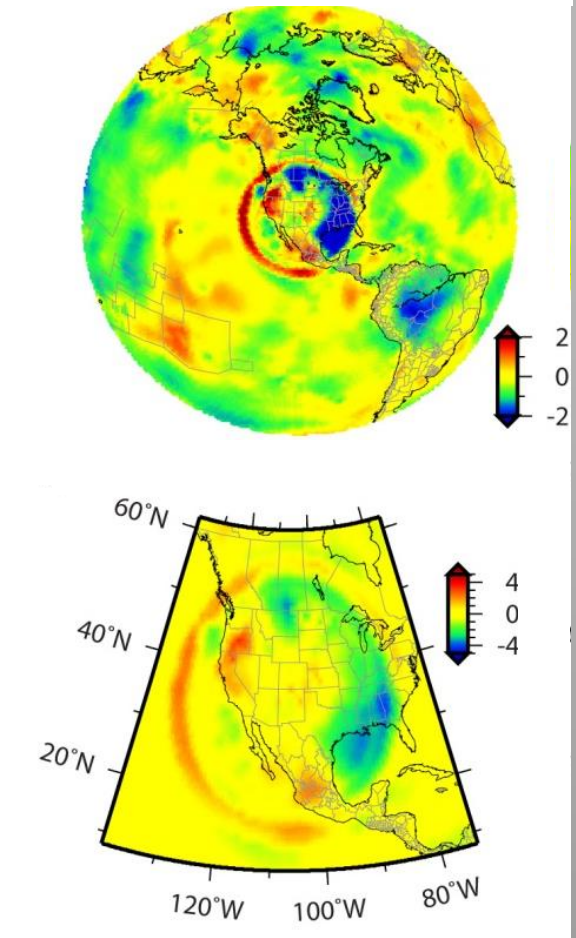
CTBTO-IDC: Source-Specific Station Corrections (SSSCs) store precomputed differences between 3D and 1D models

- ✓ Can be used with fully 3D models
  - Global implementation has limiting memory requirements even for operational computer systems
  - Very challenging for large and dynamic networks

NonLinLoc: Precomputation on a 3D grid

- ✓ Proven for static, local networks

Example of geographic correction to 1D-model travel-time prediction



From Simmons et al., 2012

CTBTO=Comprehensive Nuclear-Test-Ban Treaty Organization  
IDC=International Data Centre

# Machine learning may be the path forward for operational use of 3D models

Machine Learning (ML) is widely used for:

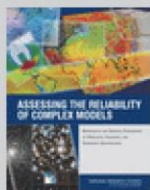
- 1) Search engines
- 2) Fraud detection
- 3) Traffic predictions
- 4) Spam filtering
- 5) Facial recognition
- 6) Speech recognition
- 7) Product recommendations

# Machine learning may be the path forward for operational use of 3D models

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- 1) Search engines
- 2) Fraud detection
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- 5) Facial recognition
- 6) Speech recognition
- 7) Product recommendations

ML for emulation of complex, computationally expensive numerical simulations



Assessing the Reliability of Complex Models: Mathematical and Statistical Foundations of Verification, Validation, and Uncertainty Quantification

Committee on Mathematical Foundations of Verification, Validation, and Uncertainty Quantification; Board on Mathematical Sciences and Their Applications, Division on Engineering and Physical Sciences, National Research Council

ISBN  
978-0-309-25634-6

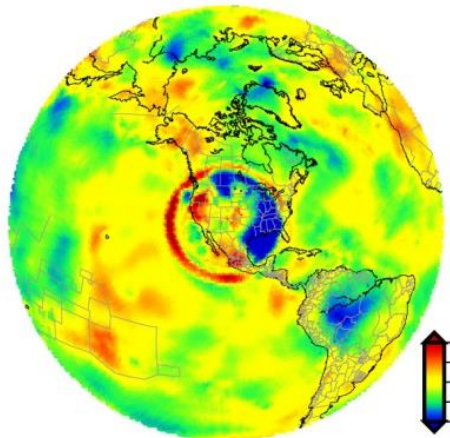
184 pages  
8 1/2 x 11  
PAPERBACK (2012)

## ***National Academy of Sciences Study***

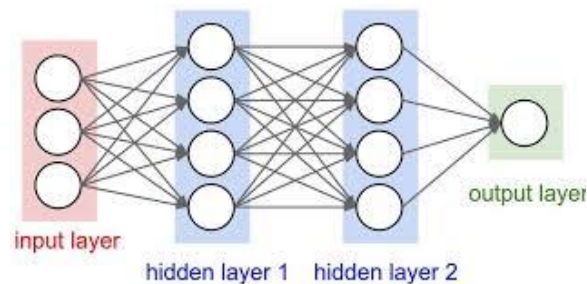
- Are machine learning estimates of full physics calculations valid?
- Paraphrasing: **ML is a powerful tool for emulating computationally intensive physics calculations when done correctly.**

# Overview of the approach for the use of ML for computation of seismic travel times

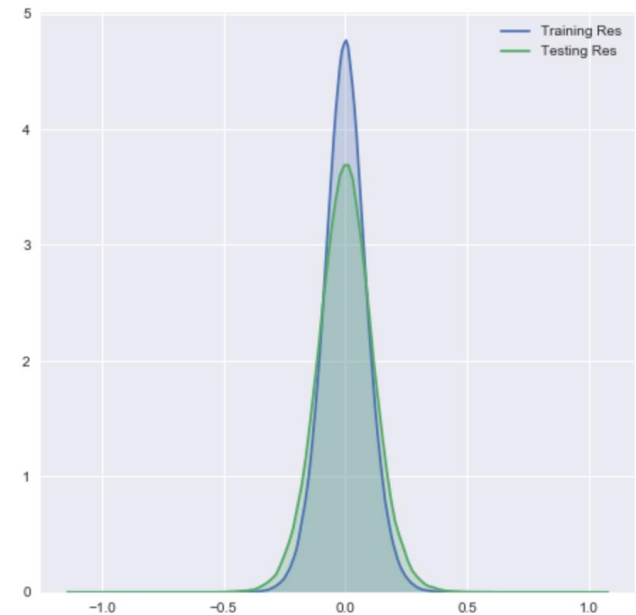
Compute Millions of travel times through the 3D model



Train a deep-learning system to emulate the travel times



Validate



Input  
Phase  
Event\_loc  
Station\_loc

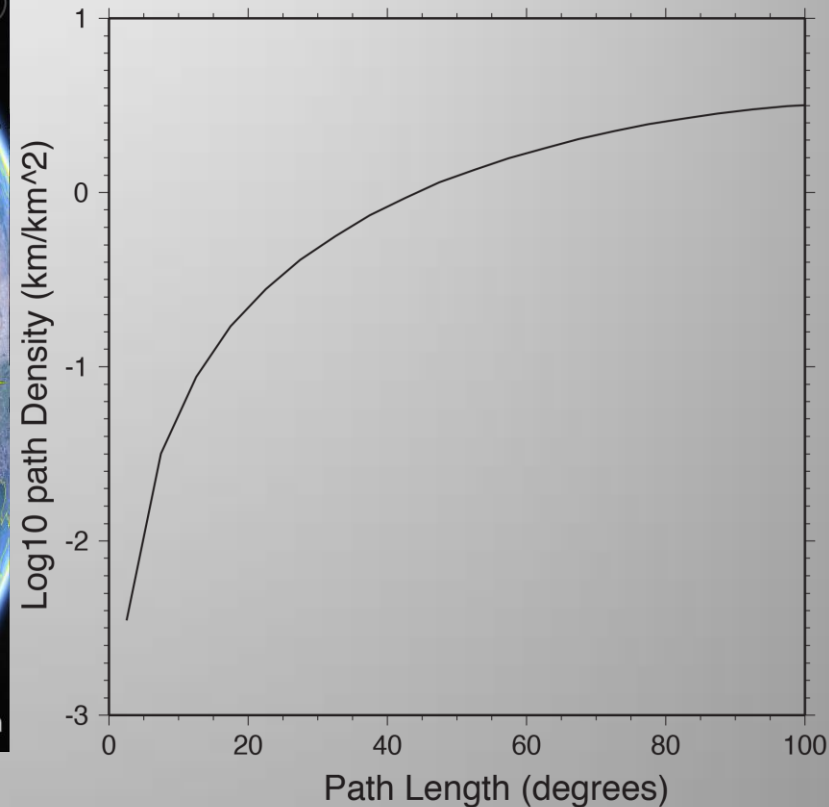
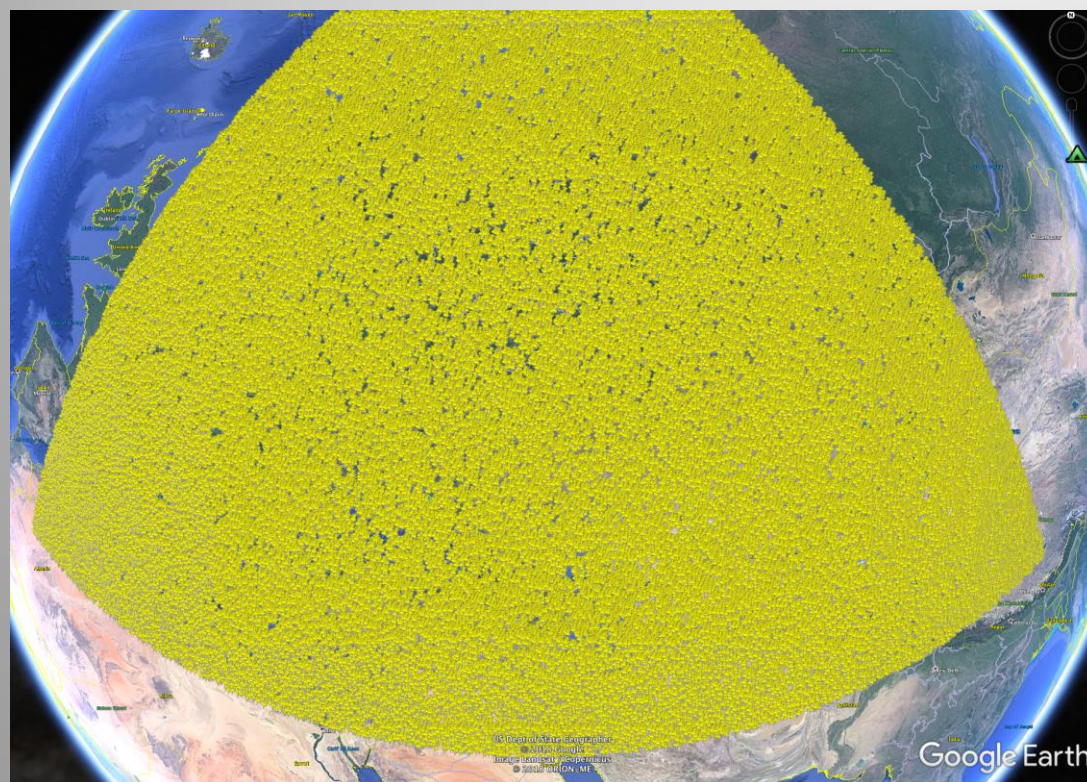
Output  
Travel time  
Uncertainty

# Global training data set

2 Million randomly selected ray paths spanning the globe

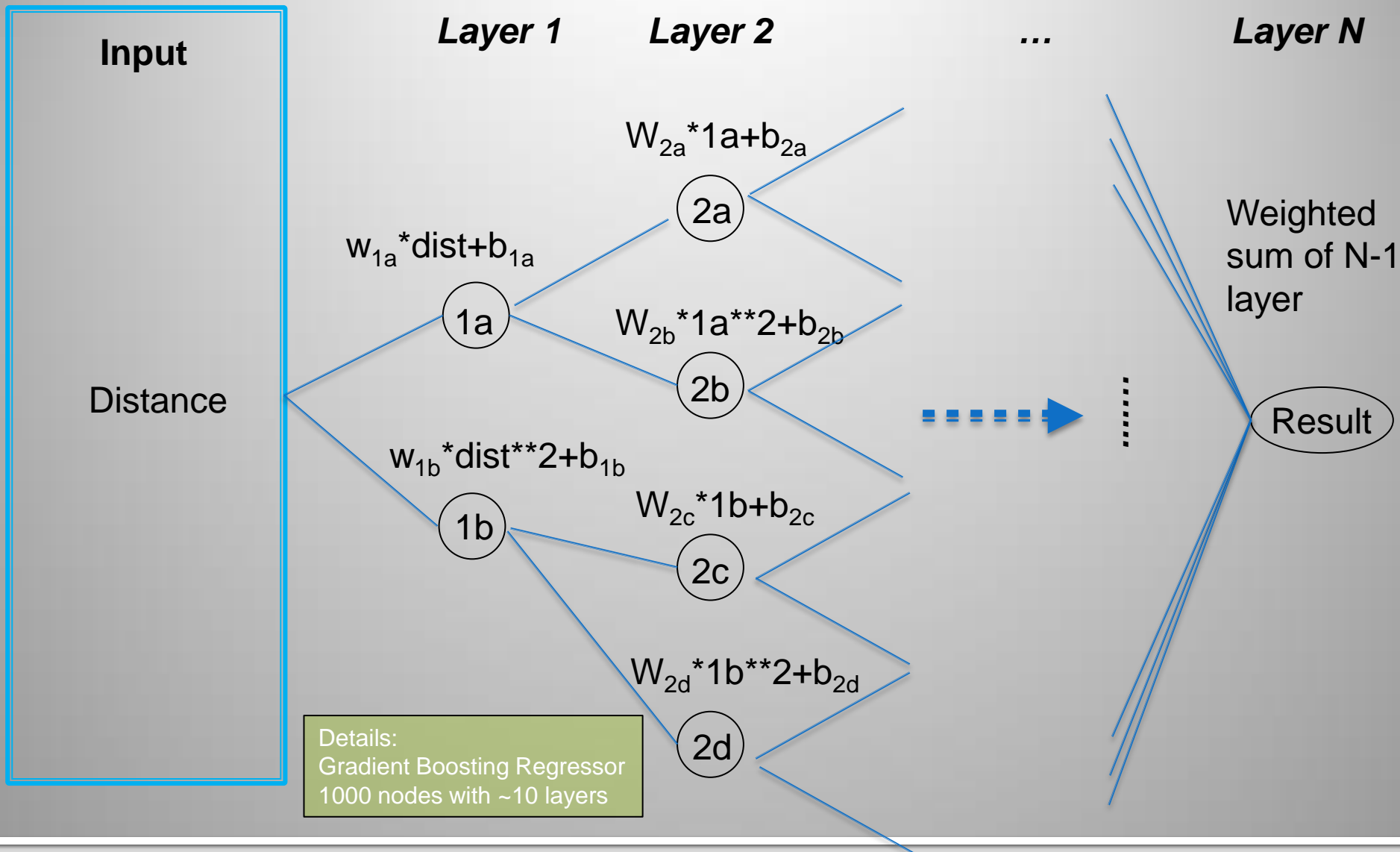
Subset of the 2M points

Sample density is dependent on path length

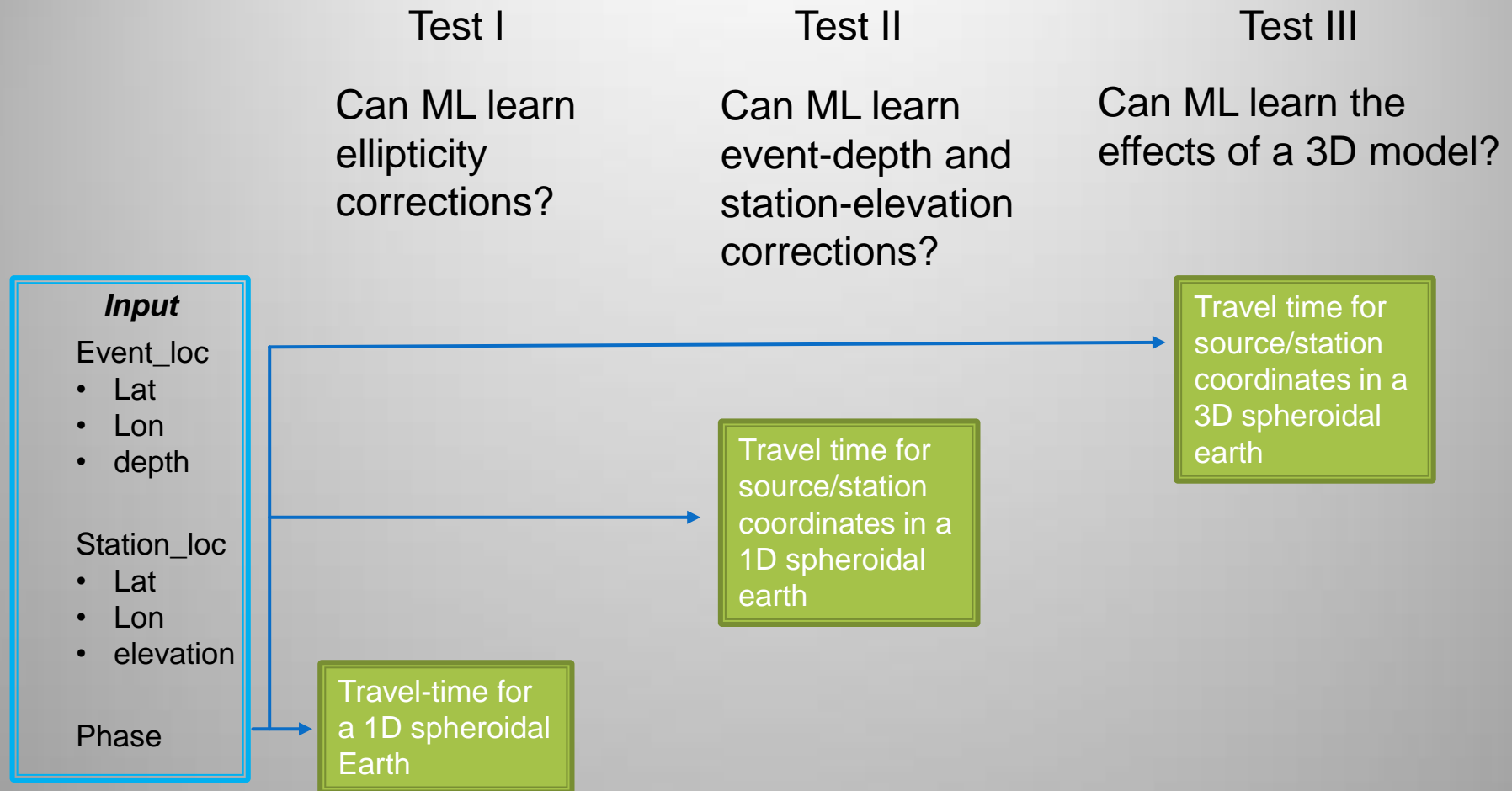


# Simplified ML model

Machine learning algorithms find optimal weights



# Progressive tests of machine learning for seismic travel time calculation



Current testing is for first-arriving P-waves

# Test I

## (spheroidal model, zero depth events)

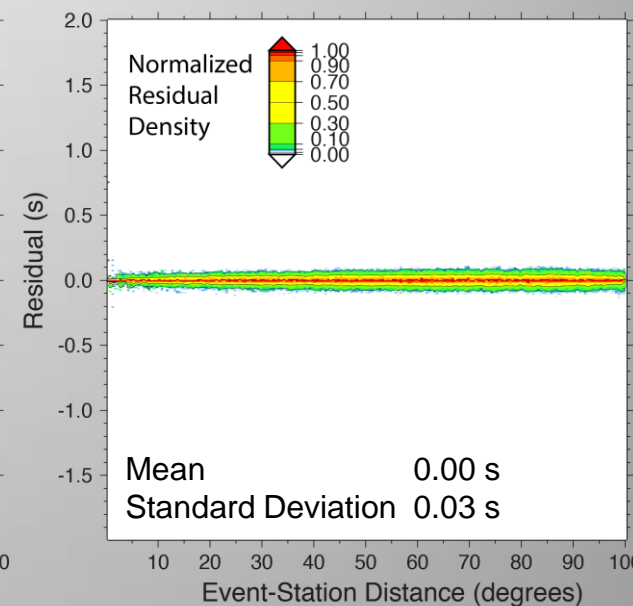
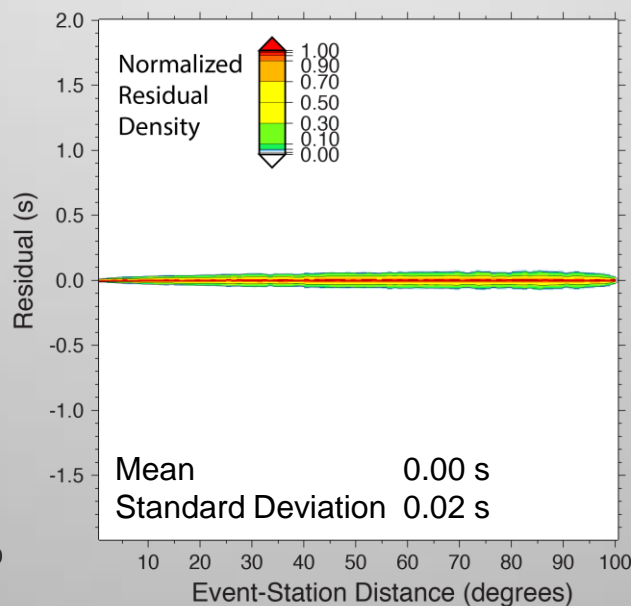
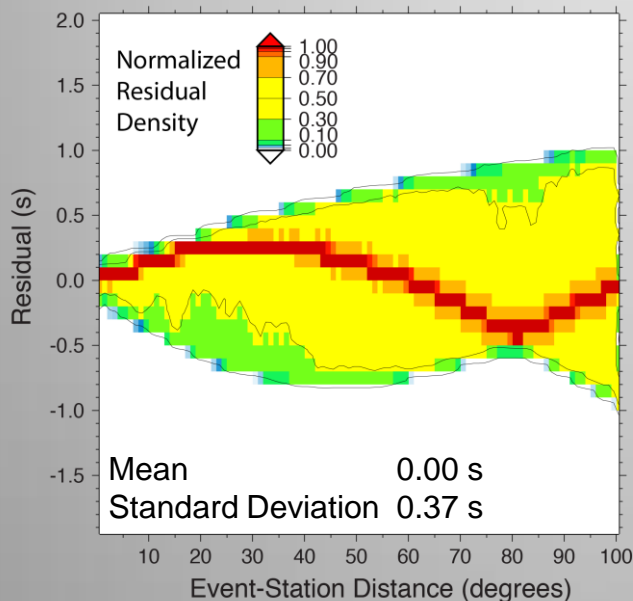
Travel Time difference  
for spherical and  
spheroidal earth model

Travel time difference between ak135, WGS-84  
model and ML\_TT

Training Set

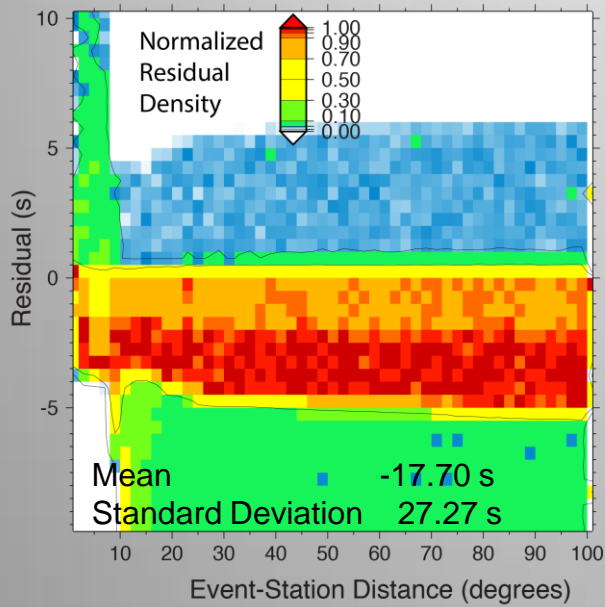
Test Set

1/3 of data reserved for testing



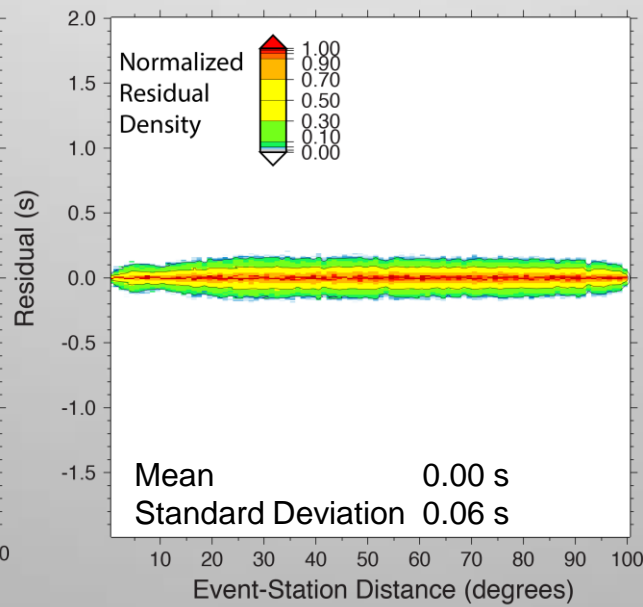
# Test Phase II (spheroidal model, 0km-660 km depth events)

Travel Time difference for surface focus and events at a range of depths



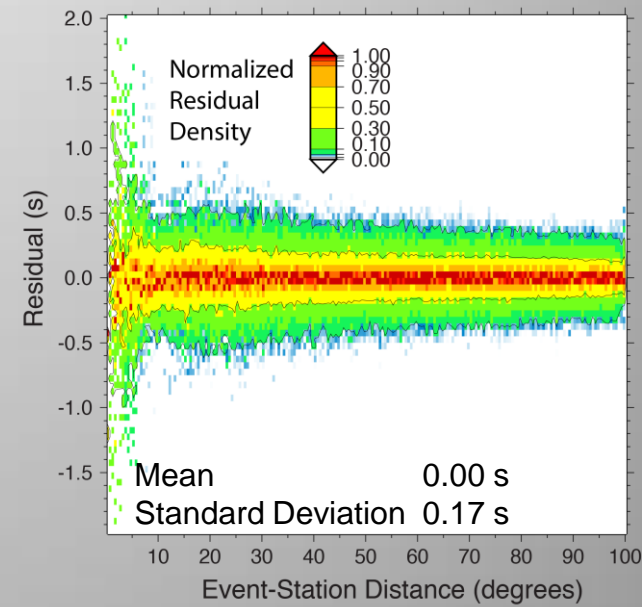
Travel time difference between ak135, WGS-84 model and ML\_TT

Training Set



Test Set

1/3 of data reserved for testing



# Test Phase III

## (3D model, 0km-660 km depth events)

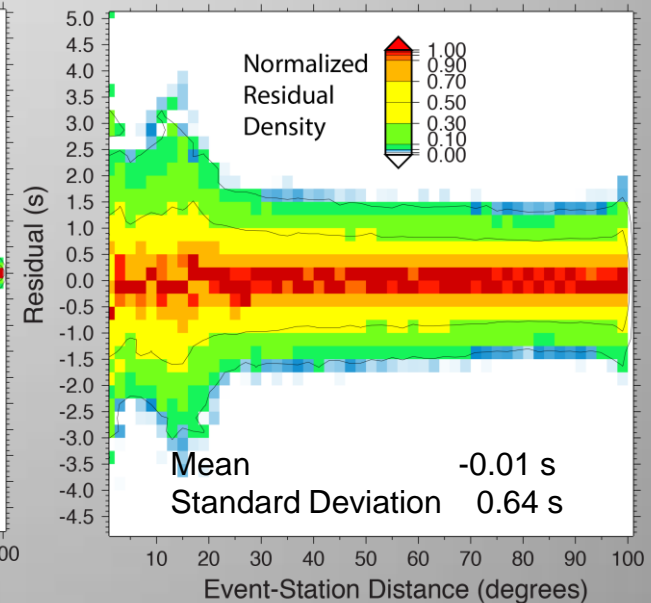
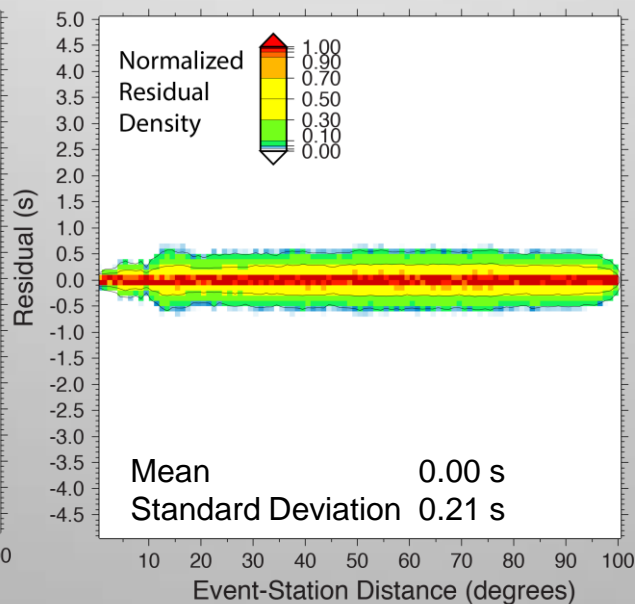
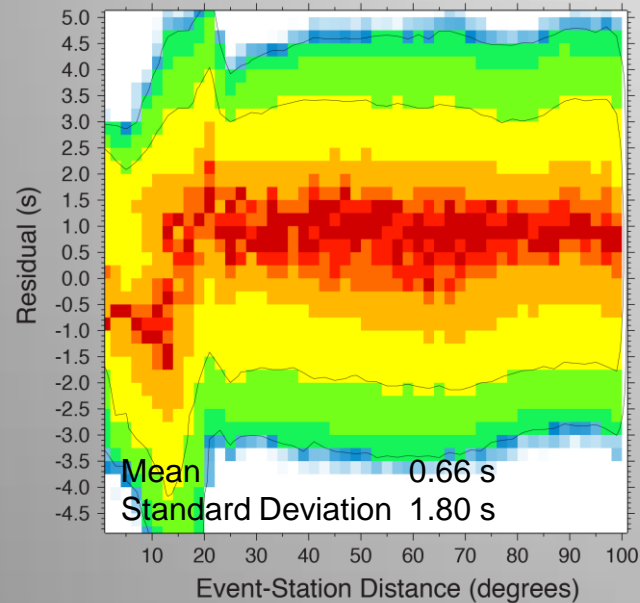
Travel Time difference  
for 3D and 1D model  
(3D model is LLNL-G3D,  
Simmons et al., 2012)

Travel time difference between 3D model and  
ML\_TT

Training Set

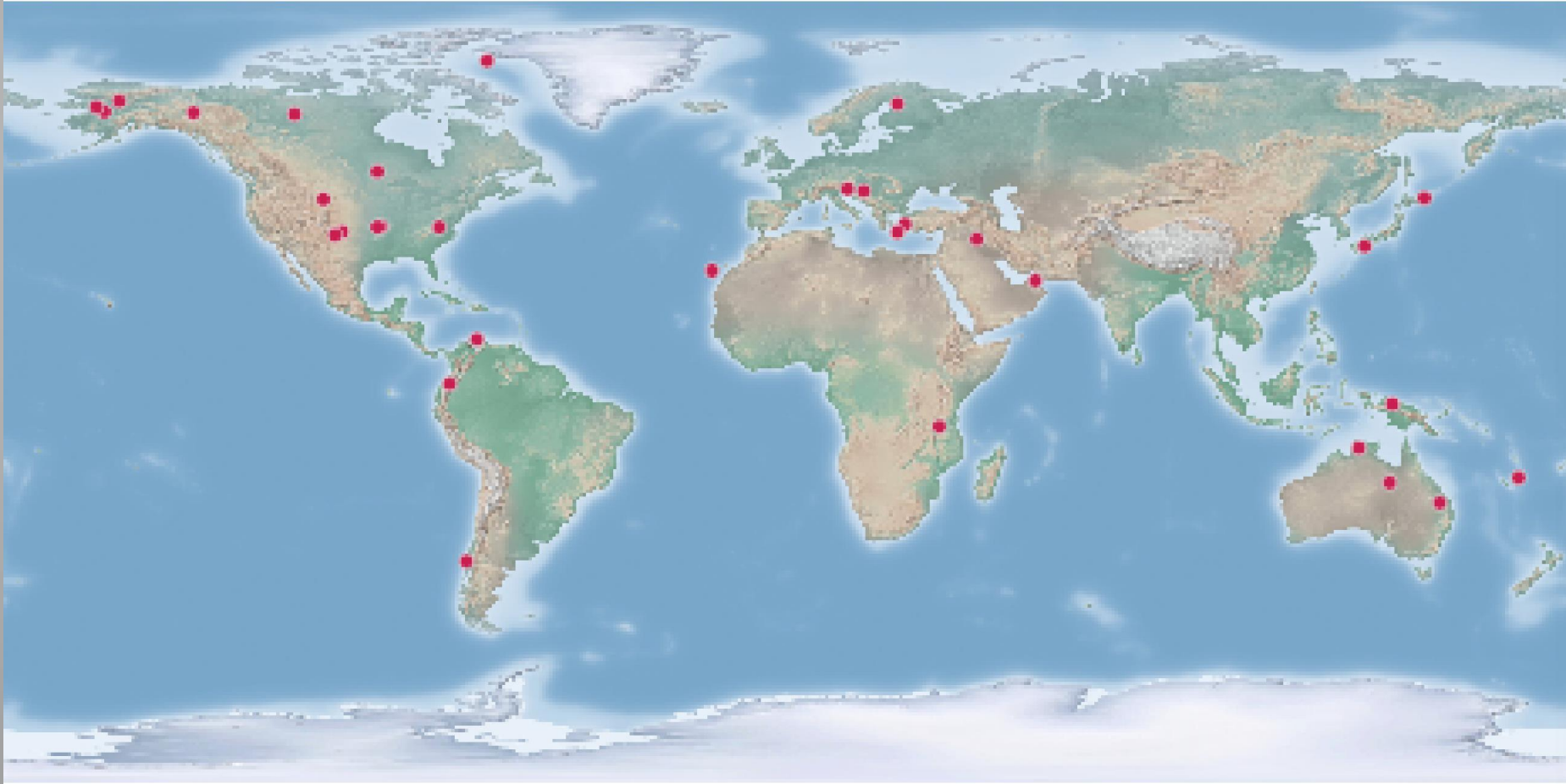
Test Set

1/3 of data reserved for testing



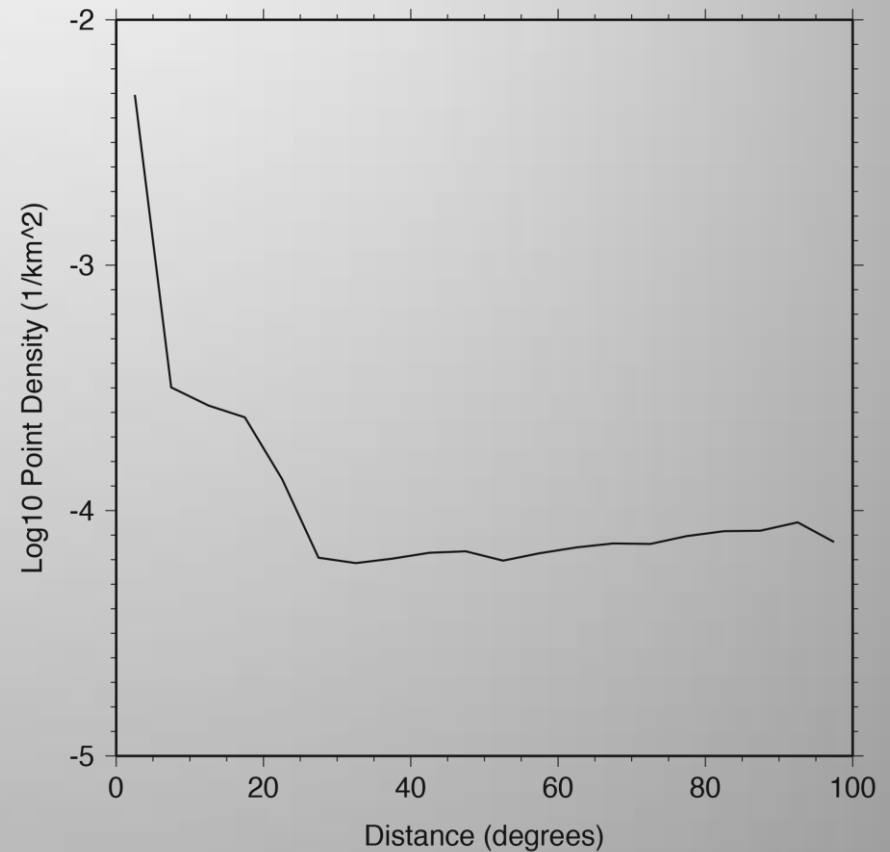
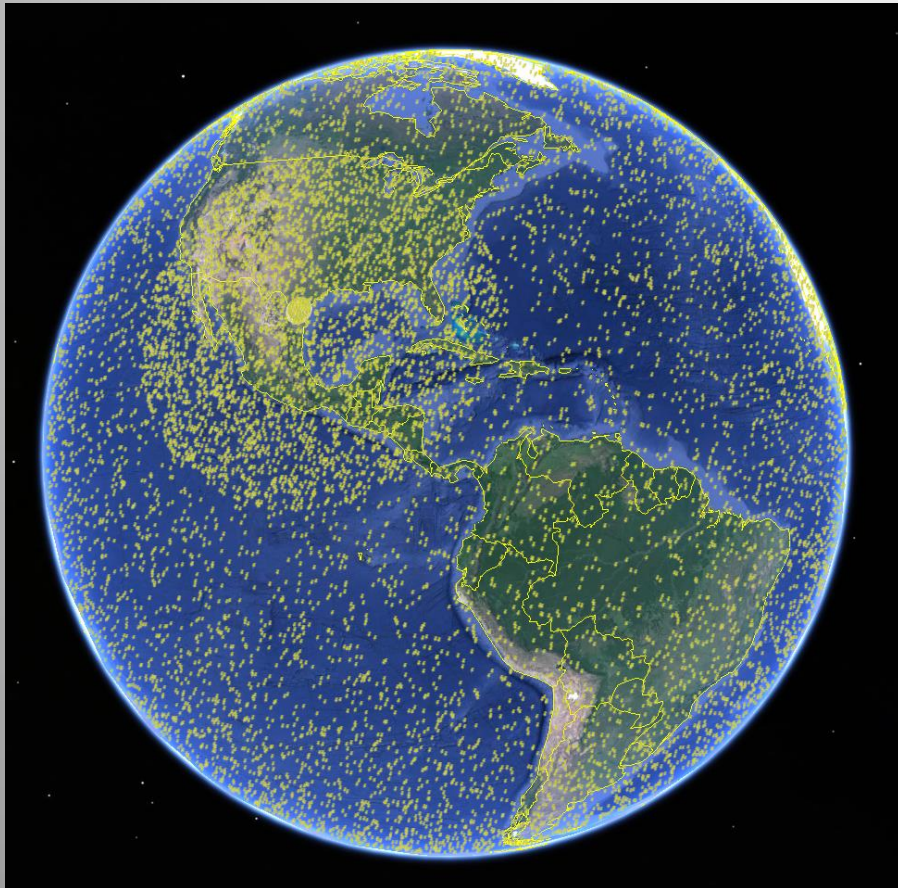
# Improve ML\_TT with station-specific training

32 randomly selected stations



# Station-specific training sets

- 32,000 paths for each network station
- Sample density is greater where travel times vary most
  - local & regional distances



# Test Phase III (*Reminder*)

## (3D model, 0km-660 km depth events)

Travel Time difference  
for 3D and 1D model

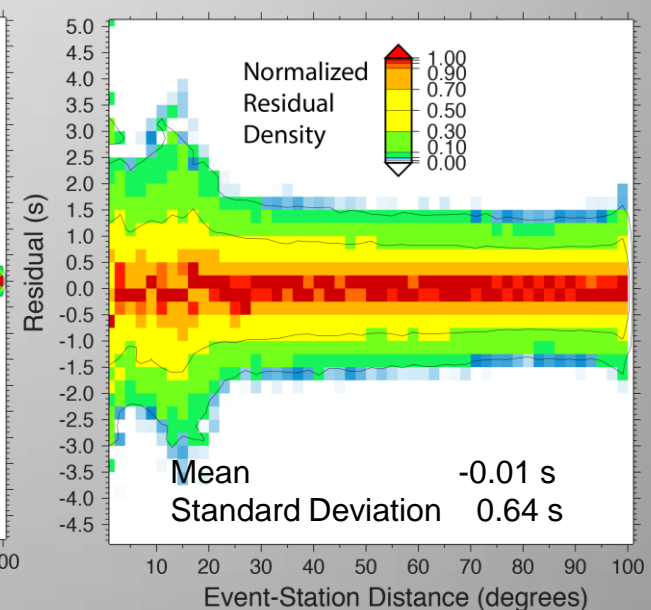
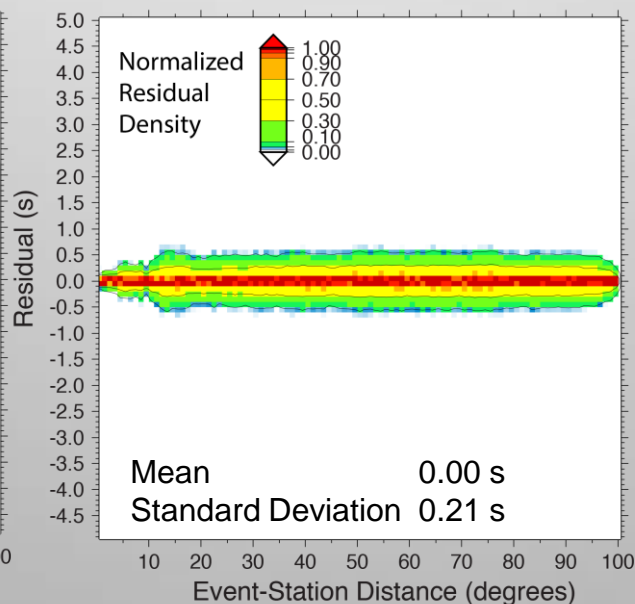
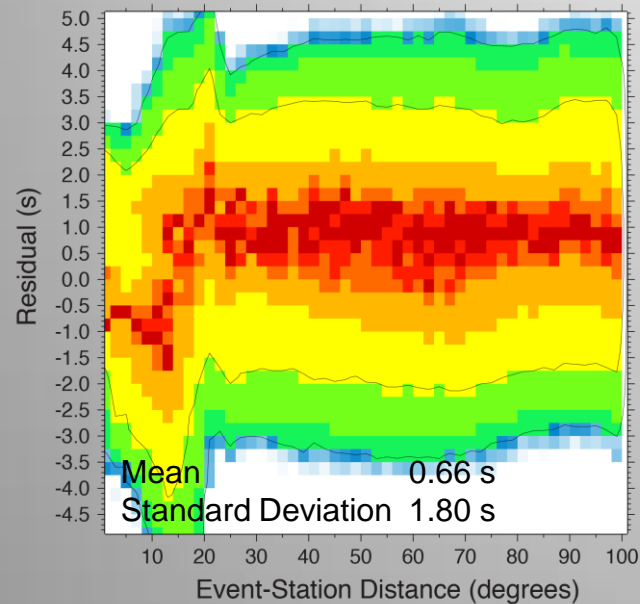
(3D model is LLNL-G3D,  
Simmons et al., 2012)

Travel time difference between 3D model and  
ML\_TT

Training Set

Test Set

1/3 of data reserved for testing



# Test Phase III<sup>+</sup> (Station-specific training) (3D model, 0km-660 km depth events)

Travel Time difference  
for 3D and 1D model

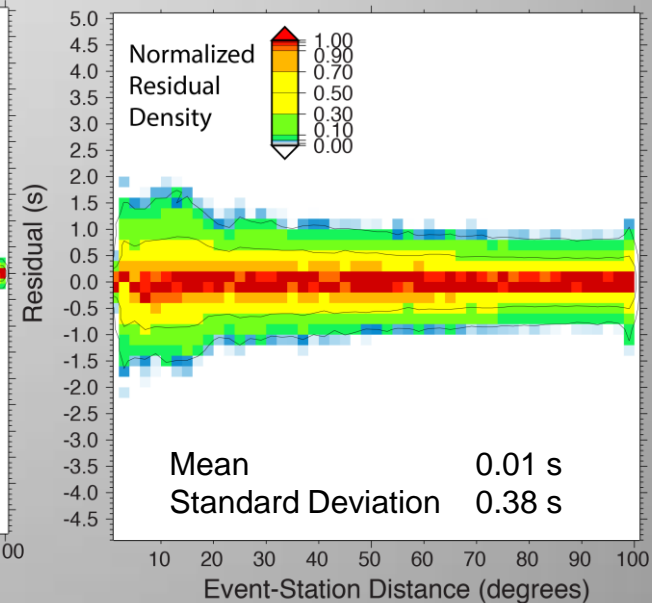
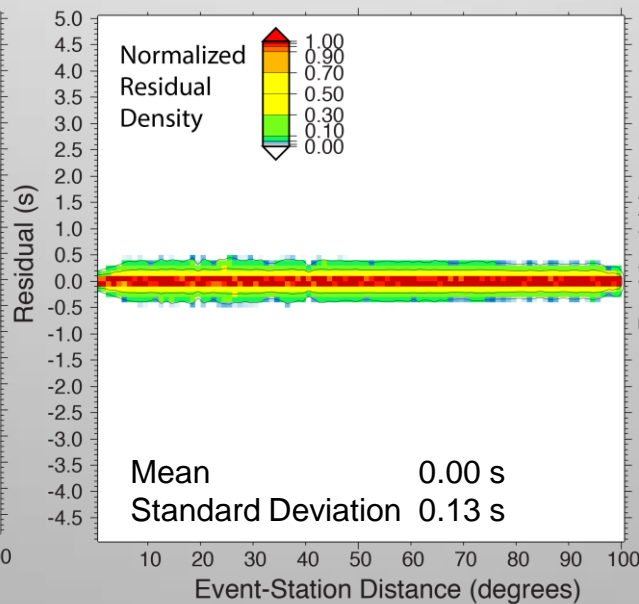
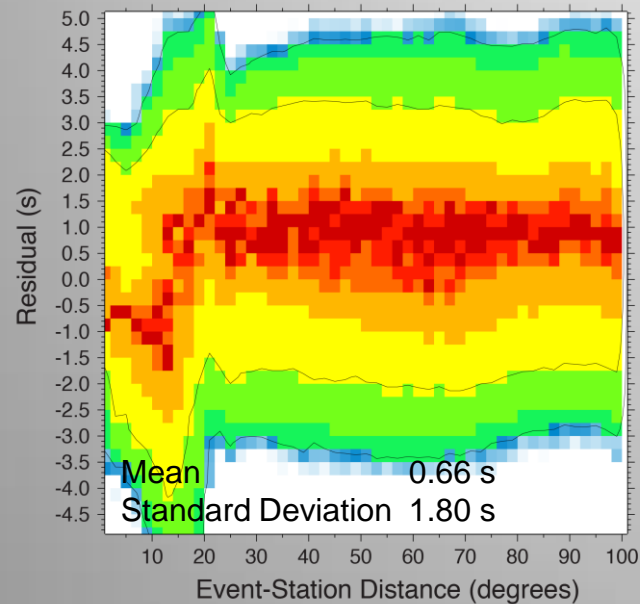
(3D model is LLNL-G3D,  
Simmons et al., 2012)

Travel time difference between 3D model and  
ML\_TT

Training Set

Test Set

1/3 of data reserved for testing



# Summary

- 3D global models can significantly improve the accuracy of seismic travel time predictions
- Computation time using a 3D model is too slow for operational systems
- Machine learning has been used to emulate expensive, full-physics simulations
- Tests show that ML emulation for seismic travel times are accurate to at least  $\sim 0.38$  seconds on average
- Computation time using ML emulation is about 10 micro seconds, well within operational needs
- More extensive training sets will further improve ML\_TT prediction accuracy.